

AMENDMENTS TO THE SPECIFICATION

Please amend the paragraph on page 2 beginning on line 6 and ending on line 23 with the following:

Accordingly, [[in one non-limiting embodiment of]] the present invention [[there is provided]] provides a hand held device comprising a handle, an operational member which folds into and out of a side of the handle, a control member for controlling the folding of the operational member, an arm which connects the control member to the operational member, a guide groove which is in the handle and which guides the control member over a path which causes the folding of the operational member, a first connecting formation which connects the arm to the operational member, and a second connecting formation which connects the operational member to the handle, the device being such that movement of the control member along the guide groove causes the folding of the operational member via the arm, the device being such that in its closed condition the operational member is folded into the handle and the first connecting formation is further away than the second connecting formation from a first end of the handle that is [[remote]] farthest from both the first and second connecting formations, and the device being such that in its open condition the operational member is folded out of the handle and the first connecting formation is nearer than the second connecting formation to the first end of the handle.

Please amend the paragraph of the Abstract beginning on line 5 and ending on line 23 with the following:

A hand held device (2) comprising a handle (4), an operational member (6) [[which folds into and out of a side (8) of the handle (4)]], a control member (10) for controlling the folding of the operational member (6), an arm (12) which connects the control member (10) to the operational member (6), a guide groove (14) [[which is in the handle (4) and]] which guides the control member (10) [[over a path which causes the folding of the operational member (6)]], a first connecting formation (16) which connects the arm (12) to the operational member (6), and a second connecting formation (18) which connects the operational member (6) to the handle (4), [[the device (2) being such that]] movement of the control member (10) along the guide groove (14) causes the folding of the operational member (6) via the arm (12), [[the device (2) being such that]] in its closed condition [[the operational member (6) is folded into the handle (4) and]] the first connecting formation (16) is further away than the second connecting formation (18) from a first end (20) of the handle (4) that is [[remote]] farthest from both the first and second connecting formations (16, 18), and [[the device (2) being such that]] in its open condition [[the operational member (6) is folded out of the handle (4) and]] the first connecting formation (16) is nearer than the second connecting formation (18) to the first end (20) [[of the handle (4)]].